

A Reliable Algorithm for Multi-Dimensional Mobile/Immobile Advection-Dispersion Equation with Variable Order Fractional

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Abstract

Objectives: Presented a modified treatment of initial boundary value problems for multi-dimensional mobile/immobile advection-dispersion equation with variable order fractional (MDMADEVF). **Methods:** we applied mixed initial and boundary conditions together using variational iteration method (VIM) to get a new initial solution at every iteration. **Findings:** The simulation results show the proposed system accurate and the utilized algorithm simple and easy to implement. **Application:** numerical examples were provided to show that variational iteration method was computationally efficient. The results were presented in tables and figures using the MathCAD 12 and Matlab software package when it is needed.

Keywords: Caputo Derivatives, Fractional Mobile / Immobile Advection-Dispersion Model.

1. Introduction

Fractional Differential Equations (FDEs) display numerous phenomena in several fields such as engineering, finance and physics¹⁻³, viscoelasticity⁴, biology⁵, fluid mechanics and chemistry⁶⁻⁷. Therefore, a growing report by applying fractional calculus in signal processing, modeling, control, electromagnetism, physics, mechanics, bioengineering, medicine and in many other areas. Numerical and approximation techniques must be used due to most FDEs do not have exact analytic solutions.

Numerical treatment based upon finite difference methods for FDEs was presented⁸⁻¹⁰. While Finite element methods were introduced to obtain the numerical solutions of FDEs¹¹⁻¹⁴. In addition, several spectral algorithms were designed for FDEs in previous reports¹⁵⁻¹⁹. In these papers, fractional order derivative is constant fractional and not variable fractional order while is constant fractional.

Advection-dispersion equation was utilized to model many chemical, physical engineering and sci-

ences of earth²⁰. Lately, researchers found that numerous dynamic processes displayed fractional order manner that might differ with space or time and showed that variable-order calculus was a natural candidate to supply an efficient mathematical framework for the depiction of complex dynamical problems²¹⁻²⁶. In other papers different variable fractional operator definitions for solving variable FDEs were discussed²⁷⁻³³.

The numerical approximation of variable fractional order partial differential equations with is relatively new, and at an early stage of development. Additionally, the most developed methods today are finite difference methods for the numerical approximation of variable-order FDEs³⁴⁻³⁷.

In the last decade, there were exceptional consideration to suggest and develop spectral methods to solve FDEs with both variable-order and fixed-order operators³⁸⁻⁴¹.

In⁴² suggested spectral collocation method for solving 1D and 2D variable-order fractional nonlinear cable equations⁴³ developed an exponentially accurate frac-

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tional spectral collocation method for solving linear/nonlinear variable-order FDEs.

In⁴⁴ proposed an accurate numerical algorithm for functional boundary value problems with variable-order fractional⁴⁵ suggested a numerical method for the time variable fractional order mobile-immobile advection-dispersion model (VFOMADM)⁴⁶ developed a numerical simulation of time VFOMADM. The primary objective of this work was to present a (VIM) with modified treatment of initial boundary value problems. The secondary objective was to use this method to study numerically the (MDMADEVF) given by:

$$\begin{aligned} & \beta_1 D_{\zeta} \Psi(w_1, w_2, \dots, w_n, \zeta) + \beta_2 D_{\zeta}^{\gamma(w_1, w_2, \dots, w_n, \zeta)} \Psi(w_1, w_2, \dots, w_n, \zeta) \\ &= -\beta_3 \sum_{i=1}^n D_{w_i} \Psi(w_1, w_2, \dots, w_n, \zeta) + \beta_4 \sum_{i=1}^n D_{w_i}^2 \Psi(w_1, w_2, \dots, w_n, \zeta) + \\ & Q(w_1, w_2, \dots, w_n, \zeta), \quad i=1, 2, \dots, n \end{aligned} \quad (1)$$

subject to the initial condition (IC):

$$\Psi(w_1, w_2, \dots, w_n, 0) = f(w_1, w_2, \dots, w_n), \quad 0 \leq w_i \leq 1$$

And the boundary conditions (BC):

$$\begin{aligned} \Psi(0, w_2, \dots, w_n, \zeta) &= k_1(w_2, w_3, \dots, w_n, \zeta), \quad 0 \leq \zeta \leq J \\ \Psi(w_1, 0, \dots, w_n, \zeta) &= k_2(w_1, w_3, \dots, w_n, \zeta) \end{aligned}$$

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$$\Psi(w_1, w_2, \dots, w_{n-1}, 0, \zeta) = k_n(w_1, w_2, \dots, w_{n-1}, \zeta)$$

$$\Psi(1, w_2, \dots, w_n, \zeta) = H_1(w_2, w_3, \dots, w_n, \zeta)$$

$$\Psi(w_1, 1, \dots, w_n, \zeta) = H_2(w_1, w_3, \dots, w_n, \zeta)$$

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$$\Psi(w_1, w_2, \dots, w_{n-1}, 1, \zeta) = H_n(w_1, w_2, \dots, w_{n-1}, \zeta)$$

Where $\beta_1, \beta_2 \geq 0, \beta_3, \beta_4 > 0, 0 < \gamma \leq \gamma(w, \zeta) \leq \bar{\gamma} \leq 1$, and, $Q, f, k_1, k_2, \dots, k_n$, and, $H_1, H_2, \dots, H_n$ are known functions, T is given constant and $D^{a(x)}$ in our problem we define in terms of Caputo variable order fractional derivatives as defined by⁴⁷⁻⁴⁸

$$D^{\alpha(w, \zeta)} f(w) = \frac{1}{\Gamma(m - \alpha(w, \zeta))} \int_0^w \frac{f^{(m)}(\zeta)}{(w - \zeta)^{\alpha(w, \zeta) - m + 1}} d\zeta$$

Where $m - 1 < \alpha(w) < m, m \in N, w > 0$.

For the Caputo variable order derivative, we have:

$$D_{L^+}^{\alpha(w)} (w - L)^n = \frac{\Gamma(n + 1)}{\Gamma(n + 1 - \alpha(w))} (w - L)^{n - \alpha(w)}$$

And

$$D_{R^-}^{\alpha(w)} (R - w)^n = \frac{\Gamma(n + 1)}{\Gamma(n + 1 - \alpha(w))} (R - w)^{n - \alpha(w)}$$

The paper is organized as follows. In section 2, modified treatment of initial boundary value. In section 3, VIM for solving (MDMADEVF). In section 4, numerical examples are solved using proposed method. Finally, we present conclusion about solution (MDMADEVF) in section 5.

2. Modified Treatment of Initial Boundary Value Problems

Usually for selecting Ψ_0 the zeroth approximation used the initial values, but in this paper, we accredited a new technique to calculate the zero the approximation Ψ_0^* by constructing a new initial solutions Ψ_n^* by mixed initial conditions with boundary conditions at every iteration as follows:

First, the initial solution can be written as:

$$\Psi_0(w_1, w_2, \dots, w_n, \zeta) = f_0(w_1, w_2, \dots, w_n) + \zeta f_1(w_1, w_2, \dots, w_n) \quad (2)$$

Where

$$\Psi(w_1, w_2, \dots, w_n, 0) = f_0(w_1, w_2, \dots, w_n),$$

$$D_{\zeta} \Psi(w_1, w_2, \dots, w_n, 0) = f_1(w_1, w_2, \dots, w_n)$$

Second, we constructed a new successive initial solution Ψ_n^* at every iteration by applying a new technique

$$\begin{aligned} \Psi_n^*(w_1, w_2, \dots, w_n, \zeta) &= \Psi_n(w_1, w_2, \dots, w_n, \zeta) + (1 - w_1^2) \\ & \left[k_1(w_2, w_3, \dots, w_n, \zeta) - \Psi_n(0, w_2, \dots, w_n, \zeta) \right] + \\ & w_1^2 \left[H_1(w_1, w_2, \dots, w_n, \zeta) - \Psi_n(0, w_2, \dots, w_n, \zeta) \right] + \dots + \\ & (1 - w) \left[k_n(w_1, w_2, \dots, w_n, \zeta) - \Psi_n(w_1, w_2, \dots, w_n, \zeta) \right] + \\ & w_n^2 \left[H_n(w_1, w_2, \dots, w_{n-1}, \zeta) - \Psi_n(w_1, w_2, \dots, w_{n-1}, 1, \zeta) \right] \end{aligned} \quad (3)$$

Where

$$\begin{aligned}\Psi(0, w_2, \dots, w_n, \zeta) &= k_1(w_2, w_3, \dots, w_n, \zeta) \\ &\vdots \\ \Psi(w_1, w_2, \dots, w_{n-1}, 0, \zeta) &= k_n(w_1, w_2, \dots, w_{n-1}, \zeta) \\ \Psi(1, w_2, \dots, w_n, \zeta) &= H_1(w_2, w_3, \dots, w_n, \zeta) \\ &\vdots \\ \Psi(w_1, w_2, \dots, w_{n-1}, 1, \zeta) &= H_n(w_1, w_2, \dots, w_{n-1}, \zeta)\end{aligned}$$

3. VIM for Solving MDMADEVF

In this section, we will apply VIM for solving MDMADEVF. Consider the general nonlinear differential equation:

$$L\Psi(w, \zeta) + N\Psi(w, \zeta) = g(w, \zeta) \quad (4)$$

Where L is a linear differential operator, N is a nonlinear operator, and g an inhomogeneous term. According to VIM:

$$\Psi_{n+1}(w, \zeta) = \Psi_n(w, \zeta) + \int_0^\zeta \lambda (L\Psi_n(\tau) + N\Psi_n(\tau) - g(\tau)) d\tau \quad (5)$$

And λ is a Lagrange multiplier which can be identified optimally via the variational theory. The subscript n indicates the n th approximation and $\tilde{\Psi}_n$ is considered as a restricted variation $\delta \tilde{\Psi}_n = 0$.

To solve problem (1), for simplicity, according to the VIM and modified treatment of initial boundary value problems, we will derive functional correction as follow:

$$\begin{aligned}\Psi_{n+1}(w, \zeta) &= \Psi_n^*(w, \zeta) + \int_0^\zeta \lambda (\beta_1 D_\zeta \Psi_n^*(w_1, w_2, \dots, w_n, \tau) \\ &+ \beta_2 D_\zeta^2 \Psi_n^*(w_1, w_2, \dots, w_n, \tau) \\ &+ \beta_3 \sum_{i=1}^n D_{w_i} \Psi_n^*(w_1, w_2, \dots, w_n, \tau) - \beta_4 \sum_{i=1}^n D_{w_i}^2 \Psi_n^*(w_1, w_2, \dots, w_n, \tau) \\ &- Q(w_1, w_2, \dots, w_n, \tau)) d\tau, i = 1, 2, \dots, n\end{aligned} \quad (6)$$

$$\text{Where } \lambda = \frac{(-1)^m (\tau - \zeta)^{m-1}}{(m-1)!}$$

4. Test Problems

In this section, we will present some examples to show efficiency and high accuracy of modified treatment of initial boundary value problems by VIM for MDMADEVF.

Example 1: Consider the following one-dimensionalequation⁴⁵⁻⁴⁶:

$$\begin{aligned}\beta_1 D_\zeta \Psi(w_1, \zeta) + \beta_2 D_\zeta^{1-0.5e^{-w_1\zeta}} \Psi(w_1, \zeta) &= -\beta_3 D_{w_1} \Psi(w_1, \zeta) \\ &+ \beta_4 D_{w_1}^2 \Psi(w_1, \zeta) + Q(w_1, \zeta)\end{aligned} \quad (7)$$

$$\text{Let } \beta_1 = \beta_2 = \beta_3 = \beta_4 = 1$$

And the source functions:

$$\begin{aligned}Q(w_1, \zeta) &= 20w_1(\zeta + 1)(1 - w_1)^2 - 20w_1^2(\zeta + 1)(1 - w_1) \\ &- 2(10\zeta + 10)(1 - w_1)^2 - 8w_1(10\zeta + 10)(1 - w_1) \\ &+ 2(10\zeta + 10)w_1^2 + 10w_1^2(1 - w_1)^2 \left(\frac{t^{5e^{-w_1\zeta}}}{\Gamma(1 + 5e^{-w_1\zeta})} \right) \\ &+ 10w_1^2(1 - w_1)^2\end{aligned}$$

Subjects to the IC:

$$\Psi(w_1, 0) = 10w_1^2(1 - w_1)^2, \quad 0 \leq w_1 \leq 1$$

And Dirichlet BC:

$$\Psi(0, \zeta) = 0 \quad 0 \leq \zeta \leq J$$

$$\Psi(1, \zeta) = 0$$

That the exact solution to this problem is:

$$\Psi(w_1, \zeta) = 10w_1^2(1 - w_1)^2(1 + \zeta), \quad 0 \leq w_1 \leq 1.$$

Table 1 displays the proposed method obtained for $J=1$ and comparison between error our method and⁴⁵⁻⁴⁶. Figures 1-2 show the plot of the numerical and the exact solution surface respectively. Table 2 presents comparison between the absolute value of the maximum errors (MEs) of proposed method and⁴⁵⁻⁴⁶.

Example 2: Consider the problem (1) with the following BC and IC:

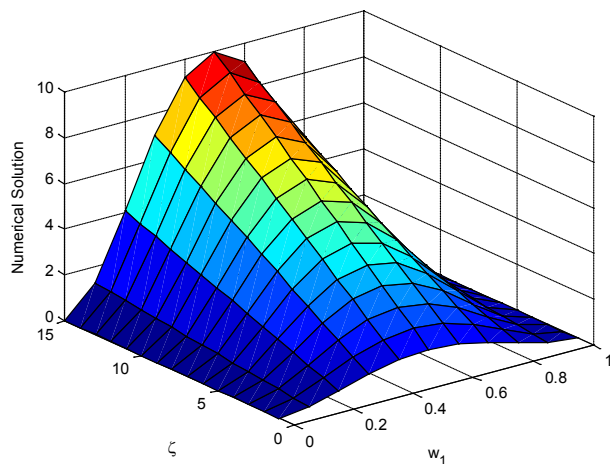
$$\begin{aligned}\beta_1 D_\zeta \Psi(w_1, \zeta) + \beta_2 D_\zeta^{0.8+0.005\cos(w_1\zeta)\sin(w_1\zeta)} \Psi(w_1, \zeta) \\ = -\beta_3 D_{w_1} \Psi(w_1, \zeta) + \beta_4 D_{w_1}^2 \Psi(w_1, \zeta) + Q(w_1, \zeta)\end{aligned} \quad (8)$$

Table 1. Numerical solution, exact solution and absolute error at $J=1$

W_1	proposed method	Exact Solution	Error of ^{f15}	Error of ^{f16}	Error of proposed method
0.1	0.162	0.162	1.56290×10^{-4}	4.77812×10^{-15}	0.000
0.2	0.512	0.512	1.40069×10^{-3}	9.13997×10^{-16}	0.000
0.3	0.882	0.882	2.97519×10^{-3}	2.76073×10^{-16}	0.000
0.4	1.152	1.152	4.29766×10^{-3}	7.07249×10^{-16}	0.000
0.5	1.250	1.250	4.97219×10^{-3}	1.04861×10^{-17}	0.000
0.6	1.152	1.152	4.80341×10^{-3}	2.33975×10^{-16}	0.000
0.7	0.882	0.882	3.81527×10^{-3}	2.30960×10^{-16}	0.000
0.8	0.512	0.512	2.27469×10^{-3}	8.43242×10^{-17}	0.000
0.9	0.162	0.162	7.20750×10^{-4}	7.95279×10^{-17}	0.000

Table 2. Comparison based on MEs of our method⁴⁵

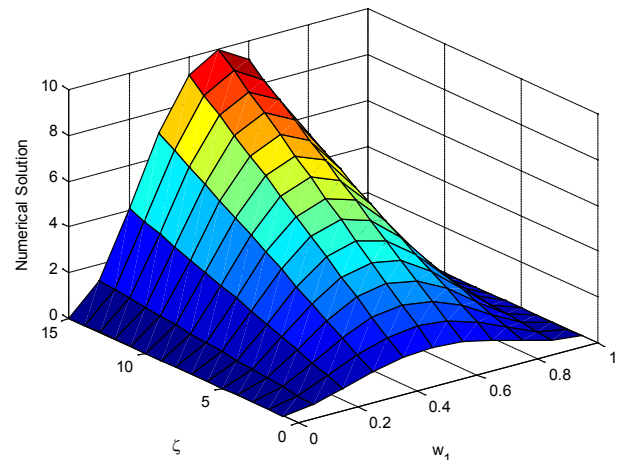
$h = \tau$	ME of ^{f15}	ME of our method
1/50	9.4391×10^{-3}	0.0000
1/100	5.0134×10^{-3}	0.0000
1/200	2.5613×10^{-3}	0.0000
1/400	1.2781×10^{-3}	0.0000


Figure 1. The surfaces show the numerical solutions $\Psi(w_1, \zeta)$ of eq. (7).

Let $\beta_1 = \beta_2 = \beta_3 = \beta_4 = 1$

And the source functions:

$$Q(w_1, \zeta) = (5\zeta + 5)(1 - w_1) - (5\zeta + 5)w_1 - 2(-10\zeta - 10) - 5w_1(1 - w_1) + 5w_1(1 - w_1) \left(\frac{\zeta^{0.2-0.5e-2\cos(w_1\zeta)\sin(w_1)}}{\Gamma(2-\zeta^{0.2-0.5e-2\cos(w_1\zeta)\sin(w_1)})} \right)$$


Figure 2. The surfaces show the exact solution $\Psi(w_1, \zeta)$ of eq. (7).

Subjects to the IC:

$$\Psi(w_1, 0) = 5w_1(1 - w_1), \quad 0 \leq w_1 \leq 1$$

And Dirichlet BC:

$$\Psi(0, \zeta) = 0$$

$$\Psi(1, \zeta) = 0$$

That the exact solution to this problem is:

$$\Psi(w_1, \zeta) = 5w_1(1 - w_1)(\zeta + 1), \quad 0 \leq w_1 \leq 1.$$

Table 3 presents comparison between the absolute value of the MEs of our method and⁴⁵. Figures 3-4 show the plot of the numerical and the exact solution surface respectively. Table 4 shows some of the analytical solutions for VFOMAD M, obtained for different values and comparison between exact solution and analytical solution.

Example 3: Consider the problem (1) with the following IC and BC:

$$\begin{aligned} &\beta_1 D_\zeta \Psi(w_1, w_2, \zeta) + \beta_2 D_\zeta^{1-0.5e^{-w_1 w_2 \zeta}} \Psi(w_1, w_2, \zeta) = \\ &-\beta_3 D_{w_1} \Psi(w_1, w_2, \zeta) - \beta_3 D_{w_2} \Psi(w_1, w_2, \zeta) \\ &+\beta_4 D_{w_1}^2 \Psi(w_1, w_2, \zeta) + \beta_4 D_{w_2}^2 \Psi(w_1, w_2, \zeta) \\ &+Q(w_1, w_2, \zeta) \end{aligned} \quad (9)$$

Let $\beta_1 = \beta_2 = \beta_3 = \beta_4 = 1$

Table 3. Comparison based on MEs of our method and⁴⁵ at $J=1$

$h = \tau$	MEs of ⁴⁵	MEs of our method
1/50	2.1562×10^{-2}	0.0000
1/100	1.0825×10^{-2}	0.0000
1/200	5.4267×10^{-3}	0.0000
1/400	2.7164×10^{-3}	0.0000

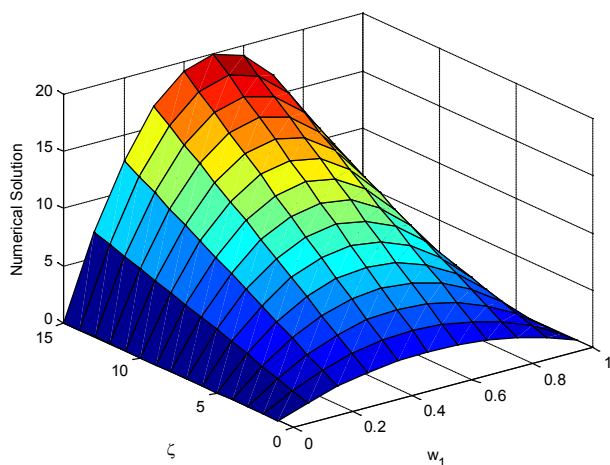


Figure 3. The surfaces show the Numerical solution $\Psi(w_1, \zeta)$ of eq. (8).

Table 4. Some of comparison between exact solution and analytical solution when $\alpha(w_1, \zeta) = 0.8 + 0.005 \cos(w_1 \zeta) \sin(w_1 \zeta)$ for example 2

W_1	ζ	Exact Solution	Variational Iteration Method	$ u_{ex}-u_{VIM} $
0	0.2	0.000	0.000	0.000
0.1	0.2	0.540	0.540	0.000
0.2	0.2	0.960	0.960	0.000
0.3	0.2	1.260	1.260	0.000
0.4	0.2	1.440	1.440	0.000
0.5	0.2	1.500	1.500	0.000
0.6	0.2	1.440	1.440	0.000
0.7	0.2	1.260	1.260	0.000
0.8	0.2	0.960	0.960	0.000
0.9	0.2	0.540	0.540	0.000
1	0.2	0.000	0.000	0.000
0	0.3	0.000	0.000	0.000
0.1	0.3	0.585	0.585	0.000
0.2	0.3	1.040	1.040	0.000
0.3	0.3	1.365	1.365	0.000
0.4	0.3	1.560	1.560	0.000
0.5	0.3	1.620	1.620	0.000
0.6	0.3	1.560	1.560	0.000
0.7	0.3	4.200	4.200	0.000
0.8	0.3	3.200	3.200	0.000
0.9	0.3	1.800	1.800	0.000
1	0.3	0.000	0.000	0.000
0	0.4	0.000	0.000	0.000
0.1	0.4	0.630	0.630	0.000
0.2	0.4	1.120	1.120	0.000
0.3	0.4	1.470	1.470	0.000
0.4	0.4	1.680	1.680	0.000
0.5	0.4	1.750	1.750	0.000
0.6	0.4	1.680	1.680	0.000
0.7	0.4	1.470	1.470	0.000
0.8	0.4	1.120	1.120	0.000
0.9	0.4	0.630	0.630	0.000
1	0.4	0.000	0.000	0.000

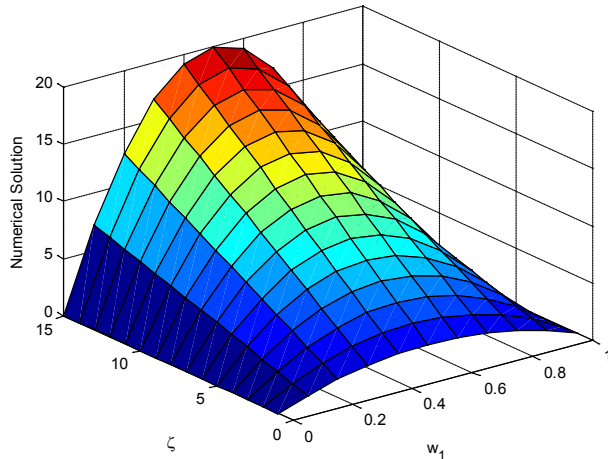


Figure 4. The surfaces show the exact solution $\Psi(w_1, \zeta)$ of eq. (8)

And the source functions:

$$\begin{aligned} \mathcal{Q}(w_1, w_2, \zeta) = & 2w_1, w_2^2 (10\zeta + 10)(1-w_1)^2 (1-w_2)^2 \\ & - 2w_1^2 w_2^2 (10\zeta + 10)(1-w_1)(1-w_2)^2 \\ & - 2w_2^2 (10 + 10)(1-w_1)^2 (1-w_2)^2 \\ & - 8w_1 w_2^2 (10\zeta + 10)(1-w_1)(1-w_2)^2 \\ & + 2w_1^2 w_2^2 (10\zeta + 10)(1-w_2)^2 \\ & + 2w_1^2 w_2 (10\zeta + 10)(1-w_1)^2 (1-w_2)^2 \\ & - 2w_1^2 w_2^2 (10\zeta + 10)(1-w_1)^2 (1-w_2) \\ & + 2w_1^2 (10\zeta + 10)(1-w_1)^2 (1-w_2)^2 \\ & + 2w_1^2 w_2 (10\zeta + 10)(1-w_1)^2 (1-w_2) \\ & + 2w_1^2 w_2^2 (10\zeta + 10)(1-w_1)^2 \\ & + 10w_1^2 w_2^2 (1-w_1)^2 (1-w_2)^2 \\ & + 10w_1^2 w_2^2 (1-w_1)^2 (1-w_2)^2 \left(\frac{\zeta^5 e^{-w_1 w_2 \zeta}}{\Gamma(1 + 5e^{-w_1 w_2 \zeta})} \right) \end{aligned}$$

Subjects to the IC:

$$\Psi(w_1, w_2, 0) = 10w_1^2 w_2^2 (1-w_1)^2 (1-w_2)^2, \quad 0 \leq w_1, w_2 \leq 1$$

And Dirichlet BC:

$$\Psi(0, w_2, \zeta) = 0$$

$$\Psi(w_1, 0, \zeta) = 0$$

$$\Psi(1, w_2, \zeta) = 0$$

$$\Psi(w_1, 1, \zeta) = 0$$

That the exact solution to this problem is:

$$\Psi(w_1, w_2, \zeta) = 10w_1^2 w_2^2 (1-w_1)^2 (1-w_2)^2 (1+\zeta), \quad 0 \leq w_1, w_2 \leq 1.$$

Table 5 shows part the analytical solutions for VFOMADM with 2-D obtained for different values and comparison between exact solution and analytical solution. Table 6

Table 5. Some of comparison between exact solution and analytical solution when $\alpha(w_1, w_2, \zeta) = 1 - 0.5e^{-w_1 w_2 \zeta}$ for example 3

$w_1 = w_2$	ζ	Exact Solution	Variational Iteration Method	$ \Psi_{ex} - \Psi_{VIM} $
0	1	0.000	0.000	0.000
0.1	1	1.312×10^{-3}	1.312×10^{-3}	0.000
0.2	1	0.013	0.013	0.000
0.3	1	0.039	0.039	0.000
0.4	1	0.066	0.066	0.000
0.5	1	0.078	0.078	0.000
0.6	1	0.066	0.066	0.000
0.7	1	0.039	0.039	0.000
0.8	1	0.013	0.013	0.000
0.9	1	1.312×10^{-3}	1.312×10^{-3}	0.000
1	1	0.000	0.000	0.000
0	2	0.000	0.000	0.000
0.1	2	1.968×10^{-3}	1.968×10^{-3}	0.000
0.2	2	0.020	0.020	0.000
0.3	2	0.058	0.058	0.000
0.4	2	0.100	0.100	0.000
0.5	2	0.117	0.117	0.000
0.6	2	0.100	0.100	0.000
0.7	2	0.058	0.058	0.000
0.8	2	0.020	0.020	0.000
0.9	2	1.968×10^{-3}	1.968×10^{-3}	0.000
1	2	0.000	0.000	0.000
0	3	0.000	0.000	0.000
0.1	3	2.624×10^{-3}	2.624×10^{-3}	0.000
0.2	3	0.026	0.026	0.000
0.3	3	0.078	0.078	0.000
0.4	3	0.133	0.133	0.000
0.5	3	0.156	0.156	0.000
0.6	3	0.133	0.133	0.000
0.7	3	0.078	0.078	0.000
0.8	3	0.026	0.026	0.000
0.9	3	2.624×10^{-3}	2.624×10^{-3}	0.000
1	3	0.000	0.000	0.000

Table 6. MEs of the numerical solution at $J=1, 2, 3$

$h = \tau$	MEs of our method
1/50	0.0000
1/100	0.0000
1/200	0.0000
1/400	0.0000

presents the absolute value of the MEs of the numerical solution at $J=1, 2, 3$.

Example 4: Consider the problem (1) with the following BC and IC:

$$\begin{aligned} \beta_1 D_\zeta \Psi(w_1, w_2, \zeta) + \beta_2 D_\zeta^{0.8+0.005\cos(w_1 w_2 \zeta) \sin(w_1 w_2)} \Psi(w_1, w_2, \zeta) = \\ -\beta_3 D_{w_1} \Psi(w_1, w_2, \zeta) - \beta_3 D_{w_2} \Psi(w_1, w_2, \zeta) \\ + \beta_4 D_{w_1}^2 \Psi(w_1, w_2, \zeta) + \beta_4 D_{w_2}^2 \Psi(w_1, w_2, \zeta) \\ + Q(w_1, w_2, \zeta) \end{aligned} \quad (10)$$

Let $\beta_1 = \beta_2 = \beta_3 = \beta_4 = 1$

And the source functions:

$$\begin{aligned} Q(w_1, w_2, \zeta) = & 2w_1 w_2 (5\zeta + 5)(1 - w_1)(1 - w_2) \\ & - w_1^2 w_2 (5\zeta + 5)(1 - w_2) \\ & + w_1^2 (5\zeta + 5)(1 - w_1)(1 - w_2) \\ & - w_1^2 w_2 (5\zeta + 5)(1 - w_1) - 2w_2 (5\zeta + 5) \\ & (1 - w_1)(1 - w_2) + 4w_1 w_2 (5\zeta + 5)(1 - w_2) \\ & + 2w_1^2 (5\zeta + 5)(1 - w_1) + 5w_1^2 w_2 (1 - w_1)(1 - w_2) \\ & + 5w_1 w_2 (1 - w_1)(1 - w_2) \left(\frac{\zeta^{0.2-0.5e-2\cos(w_1 w_2 \zeta) \sin(w_1 w_2)}}{\Gamma(2-\zeta^{0.2-0.5e-2\cos(w_1 w_2 \zeta) \sin(w_1 w_2)})} \right) \end{aligned}$$

Subjects to the IC:

$$\Psi(w_1, w_2, 0) = 5w_1(1 - w_1)(1 - w_2), \quad 0 \leq w_1, w_2 \leq 1$$

And Dirichlet BC:

$$\Psi(0, w_2, \zeta) = 0$$

$$\Psi(w_1, 0, \zeta) = 0$$

$$\Psi(1, w_2, \zeta) = 0$$

$$\Psi(w_1, 1, \zeta) = 0$$

That the exact solution to this problem is:

$$\begin{aligned} \Psi(w_1, w_2, \zeta) = 5w_1 w_2 (1 - w_1)(1 - w_2)(\zeta + 1), \\ 0 \leq w_1, w_2 \leq 1 \end{aligned}$$

Table 7 shows part the analytical solutions for VFOMADM with 2-D obtained for different values and comparison between exact solution and analytical solution. Table 8 presents the absolute value of the MEs of the numerical solution.

Table 7. Some of comparison between exact solution and analytical solution when $\alpha(w_1, w_2, \zeta) = 0.8 + 0.005\cos(w_1 w_2 \zeta) \sin(w_1 w_2)$ for example 4

$w_1 = w_2$	ζ	Exact Solution	Variational Iteration Method	$ \Psi_{ex} - \Psi_{VIM} $
0	3	0.00000	0.00000	0.000
0.1	3	0.01600	0.01600	0.000
0.2	3	0.10240	0.10240	0.000
0.3	3	0.26460	0.26460	0.000
0.4	3	0.46080	0.46080	0.000
0.5	3	0.62500	0.62500	0.000
0.6	3	0.69120	0.69120	0.000
0.7	3	0.61740	0.61740	0.000
0.8	3	0.40960	0.40960	0.000
0.9	3	0.14600	0.14600	0.000
1	3	0.00000	0.00000	0.000
0	4	0.00000	0.00000	0.000
0.1	4	0.02000	0.02000	0.000
0.2	4	0.12800	0.12800	0.000
0.3	4	0.33075	0.33075	0.000
0.4	4	0.57600	0.57600	0.000
0.5	4	0.78125	0.78125	0.000
0.6	4	0.86400	0.86400	0.000
0.7	4	0.77175	0.77175	0.000
0.8	4	0.51200	0.51200	0.000
0.9	4	0.18200	0.18200	0.000
1	4	0.00000	0.00000	0.000

Table 8. MEs of the numerical solution at $J = 1, 2, 3$

$h = \tau$	MEs of our method
0.200	0.0000
0.100	0.0000
0.050	0.0000
0.025	0.0000

5. Conclusion

In this paper, the results obtained for modified treatment of initial boundary conditions for the MDMADEVF were accurate. This algorithm was simple and easy to implement. The numerical results demonstrated that the method was accurate. On the other hand, reliable and converges faster with less computation when compared with other methods in the literature.

6. References

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